

## Determination of fracture parameters for a bi-material center cracked plate subjected to biaxial loading using FEOD method

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### ABSTRACT

Fracture parameters of a bi-material plate containing a center crack and subjected to biaxial tensile loading was calculated numerically. Based on the crack tip stress field obtained numerically in a bi-material joint and using the finite element over deterministic (FEOD) method, the stress intensity factors ( $K_I$  and  $K_{II}$ ) and also non-singular  $T$ -stress terms, were determined for different material properties and biaxial loading cases. Due to asymmetry of loading and material properties in the investigated dissimilar plate, the center crack experiences mixed mode I/II fracture in general. By increasing the bi-material constant value, which shows the difference between the mechanical properties of two materials, the amplitude of stress intensity factor decreases. The obtained results from this method were in good agreement with the displacement field method previously reported by other researchers.

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## 1. Introduction

Fracture growth from the tip of cracks in the interface of bi-material components is one of the major failure modes in such materials. Bi-material joints are frequently used in various engineering structures such as dentin/restorative (Ensaff et al., 2001; Toparli & Aksoy, 1998), bone/cement (Wang & Agrawal, 2000) ceramic/ceramic (Mirsayar and Park, 2016), ceramic/metal (Hutchinson & Suo, 1992; Mirsayar, 2013; Mirsayar & Samaei 2014), rock/concrete (Zhong et al., 2011), asphalt concrete/overlayer or bridge deck (Hakimzadeh et al., 2012) and etc. Due to some technical problems such as lack of suitable bonding, a crack may initiate in the interface of bi-material and then can propagate during service life of such joints because of applied loads and external or internal stresses. In practice, bi-material cracked components experience mixed mode I/II deformations under in-plane loads due to

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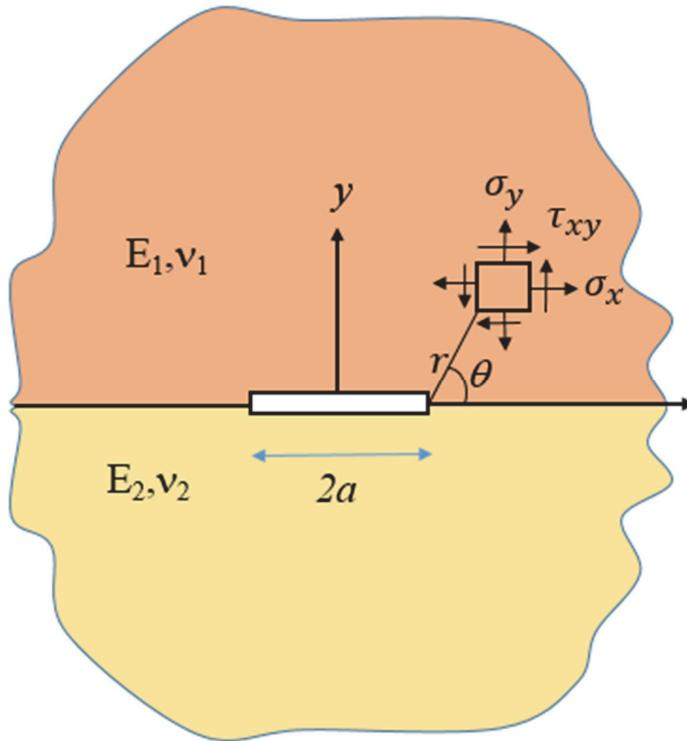
complex type of loading and also asymmetry of material at the interface. Such cracks may grow along the interface in the weak joints or kink into one of the materials in strong interfaces. In order to study the onset of interface fracture based on the approach of fracture mechanics, the stress/strain field at the tip of crack should be known. Some researchers have investigated the interface fracture problem using either crack tip stress or displacement fields. Williams (1959), Rice and Sih (1965), Asaro et al. (1993), Ravichandran and Ramesh (2005), Morioka and Sun (2010), Mirsayar (2014), Mirsayar et al. (2014) are to name a few. For example, Williams (1959) outlined the stress field for the general bi-material interface problem. The elastic stress field around a bi-material crack tip can be written as following equation in the cartesian coordinates:

$$\begin{bmatrix} \sigma_x^m \\ \sigma_y^m \\ \tau_{xy}^m \end{bmatrix} = \sum_{N=0,2,4,\dots}^{\infty} \frac{k_{IN}}{Q} r^{\frac{(N-1)}{2}} \left\{ \begin{array}{l} S^m \left\{ 3 \cos \left[ \frac{N-1}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] - (N-1) \sin \theta \sin \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] + 2 \varepsilon \sin \theta \cos \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] \right\} - \frac{1}{S^m} \cos \left[ \frac{N-1}{2} \theta + \varepsilon \ln \left( \frac{r}{L} \right) \right] \\ S^m \left\{ \cos \left[ \frac{N-1}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] + (N-1) \sin \theta \sin \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] - 2 \varepsilon \sin \theta \cos \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] \right\} + \frac{1}{S^m} \cos \left[ \frac{N-1}{2} \theta + \varepsilon \ln \left( \frac{r}{L} \right) \right] \\ S^m \left\{ -\sin \left[ \frac{N-1}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] - (N-1) \sin \theta \cos \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] - 2 \varepsilon \sin \theta \sin \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] + \frac{1}{S^m} \sin \left[ \frac{N-1}{2} \theta + \varepsilon \ln \left( \frac{r}{L} \right) \right] \right\} \end{array} \right\} + \\ \sum_{M=1,3,5,\dots}^{\infty} \frac{k_{IM}}{R(m)} r^{\frac{(M-1)}{2}} \left\{ \begin{array}{l} 4 \cos \left[ \frac{M-1}{2} \theta \right] - (M-1) \sin \theta \sin \left[ \frac{M-3}{2} \theta \right] \\ (M-1) \sin \theta \sin \left[ \frac{M-3}{2} \theta \right] \\ -2 \sin \left[ \frac{M-1}{2} \theta \right] - (M-1) \sin \theta \cos \left[ \frac{M-3}{2} \theta \right] \end{array} \right\} + \\ \sum_{N=0,2,4,\dots}^{\infty} \frac{k_{IIN}}{Q} r^{\frac{(N-1)}{2}} \left\{ \begin{array}{l} S^m \left\{ 3 \sin \left[ \frac{N-1}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] + (N-1) \sin \theta \cos \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] + 2 \varepsilon \sin \theta \sin \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] \right\} + \frac{1}{S^m} \sin \left[ \frac{N-1}{2} \theta + \varepsilon \ln \left( \frac{r}{L} \right) \right] \\ S^m \left\{ \sin \left[ \frac{N-1}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] - (N-1) \sin \theta \cos \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] - 2 \varepsilon \sin \theta \cos \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] \right\} - \frac{1}{S^m} \sin \left[ \frac{N-1}{2} \theta + \varepsilon \ln \left( \frac{r}{L} \right) \right] \\ S^m \left\{ \cos \left[ \frac{N-1}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] - (N-1) \sin \theta \sin \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] + 2 \varepsilon \sin \theta \cos \left[ \frac{N-3}{2} \theta - \varepsilon \ln \left( \frac{r}{L} \right) \right] \right\} + \frac{1}{S^m} \cos \left[ \frac{N-1}{2} \theta + \varepsilon \ln \left( \frac{r}{L} \right) \right] \end{array} \right\} + \\ \sum_{M=1,3,5,\dots}^{\infty} \frac{k_{IIM}}{R(m)} r^{\frac{(M-1)}{2}} \left\{ \begin{array}{l} 2 \sin \left[ \frac{M-1}{2} \theta \right] + (M-1) \sin \theta \sin \left[ \frac{M-3}{2} \theta \right] \\ 2 \sin \left[ \frac{M-1}{2} \theta \right] - (M-1) \sin \theta \cos \left[ \frac{M-3}{2} \theta \right] \\ -(M-1) \sin \theta \sin \left[ \frac{M-3}{2} \theta \right] \end{array} \right\} \end{array} \right\} \quad (1)$$

where,  $N$  and  $M$ , are the terms of mode I and mode II parameters in the William's series expansion, respectively the constants of singular terms in Eq. (1) are known as the modes I and II stress intensity factors ( $K_I$  and  $K_{II}$ ). The coefficient of the second term in this equation (which is non-singular stress term) is called  $T$ -stress.  $r$  and  $\theta$  are polar coordinates as defined in Fig. 1 for a biomaterial crack tip and  $L$  is a characteristic length. In comparison with the crack tip stress field in a homogenous medium (which its stress singularity is in the form of  $r^{-1/2}$ , the character of singularity changes to  $r^{-1/2+i\varepsilon}$  for bi-materials, in which  $\varepsilon$  is the bi-material constant defined as :

$$\varepsilon = \frac{1}{2\pi} \left( \frac{G_2 K_1 + G_1}{G_1 K_2 + G_2} \right) \quad (2)$$

where  $G_m$  is the shear modulus,  $\kappa_m = (3 - v_m)/(1 + v_m)$  for plane stress and  $3-4v_m$  for plane strain. Also in Eqs. 1 and 2,  $m = (1,2)$  denotes material number of bi-material joint. Other constants used for defining material-1, in Eq. 1 are:  $= 2\sqrt{2\pi} \cosh(\pi\varepsilon)$ ,  $S^{(1)} = e^{-\varepsilon(\pi-\beta)}$ ,  $R^{(1)} = \sqrt{2\pi}(1 + \omega)$ ,  $\omega = \frac{(1+k_1)G_2}{(1+k_2)G_1}$ . The stress field expressions for material-2 can be obtained by replacing  $e^{-\varepsilon\pi}$  by  $e^{+\varepsilon\pi}$ ,  $e^{+\varepsilon\pi}$  by  $e^{-\varepsilon\pi}$ ,  $\omega$  by  $1/\omega$  and replacing the corresponding  $R^{(2)}$  and  $S^{(2)}$  into the Eq. 1 (Ravichandran and Ramesh 2005).



**Fig. 1.** Stress field in the vicinity of interface crack initiated in a bi-material medium

Three fracture parameters ( $K_I, K_{II}$  and  $T$ ) that define the crack tip stress field for a bi-material joint can then be used for evaluating the onset of interface fracture via the available fracture theories such as (Mirsayar, 2014). Therefore, it is necessary to determine these parameters for any given interface crack problem with any arbitrary geometry, material type and loading conditions. Since there is no general analytical solution for determining these fracture parameters in bi-material joints, the use of numerical methods are powerful tools for computing them. The commercial finite element codes can be successfully used for computing the fracture parameters (Abd-Elhady, 2013; Ayatollahi & Aliha, 2007; 2009, Ayatollahi et al., 2011; Aliha et al., 203, 2015). However, for bi-material interface fracture problems, the available finite element codes may not provide these parameters directly and with good accuracy. Hence in this paper, as a typical bi-material interface problem, the fracture parameters of a bi-material center crack plate subjected to different biaxial loading conditions are computed numerically from its crack tip stress field and by employing a finite element over deterministic (FEOD) method. It is shown that the stress based FEOD method can provide accurate results for the fracture parameters of the bi-material center cracked plate.

## 2. Finite element over deterministic (FEOD) method

The over-deterministic method makes use of a large number of data points to determine a small set of unknown coefficients from a large system of equations (Ayatollahi & Nejati 2011). For example and as a practical application, the FEOD method can be used for determining a selected number of coefficients in the William's series expansion form the stress components which can be obtained from finite element analysis. In order to use the FEOD method for a bi-material crack medium, the following relation between the stress components and constants of the William's series expansion can be written:

$$[\sigma]_{2k \times 1} = [C]_{2k \times (N+M+2)} [X]_{(N+M+2) \times 1} \quad (3)$$

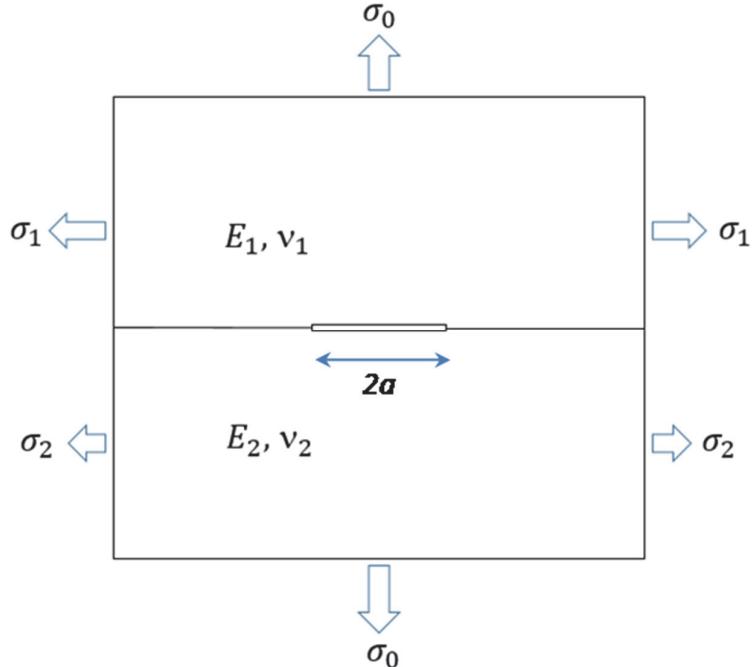
where  $\sigma$  is the components of stress tensor,  $C$  is a matrix that its components are functions of  $r$  and  $\theta$ , and  $X$  is the matrix of unknown variables (i.e. the Williams constants). By selecting a large number of nodes around the crack tip and substituting their positions and stresses into Eq. (3), a linear set of simultaneous equations is obtained. By considering the stresses of  $k$  nodes near the crack tip, the set of equations can be expanded in the following matrix form:

$$\begin{bmatrix} \sigma_{x1}^m \\ \sigma_{x2}^m \\ \vdots \\ \sigma_{y1}^m \\ \sigma_{y2}^m \\ \vdots \\ \sigma_y^m \\ \sigma_{xy1}^m \\ \sigma_{xy2}^m \\ \sigma_{xy}^m \end{bmatrix} = \begin{bmatrix} f_1^{lm}(r_1, \theta_1) & \dots & f_N^{lm}(r_1, \theta_1) & f_1^{llm}(r_1, \theta_1) & f_3^{llm}(r_1, \theta_1) & f_4^{llm}(r_1, \theta_1) & \dots & f_M^{llm}(r_1, \theta_1) & f_0 & 0 & f_2^{llm}(r_1, \theta_1) \\ f_1^{lm}(r_2, \theta_2) & \dots & f_N^{lm}(r_2, \theta_2) & f_1^{llm}(r_2, \theta_2) & f_3^{llm}(r_2, \theta_2) & f_4^{llm}(r_2, \theta_2) & \dots & f_M^{llm}(r_2, \theta_2) & f_0 & 0 & f_2^{llm}(r_2, \theta_2) \\ \vdots & \vdots \\ f_1^{lm}(r_k, \theta_k) & \dots & f_N^{lm}(r_k, \theta_k) & f_1^{llm}(r_k, \theta_k) & f_3^{llm}(r_k, \theta_k) & f_4^{llm}(r_k, \theta_k) & \dots & f_M^{llm}(r_k, \theta_k) & f_0 & 0 & f_2^{llm}(r_k, \theta_k) \\ g_1^{lm}(r_1, \theta_1) & \dots & g_N^{lm}(r_1, \theta_1) & g_1^{llm}(r_1, \theta_1) & g_3^{llm}(r_1, \theta_1) & g_4^{llm}(r_1, \theta_1) & \dots & g_M^{llm}(r_1, \theta_1) & 0 & g_0 & g_2^{llm}(r_1, \theta_1) \\ g_1^{l'}(r_2, \theta_2) & \dots & g_N^{l'}(r_2, \theta_2) & g_1^{ll'}(r_2, \theta_2) & g_3^{ll'}(r_2, \theta_2) & g_4^{ll'}(r_2, \theta_2) & \dots & g_M^{ll'}(r_2, \theta_2) & 0 & g_0 & g_2^{ll'}(r_2, \theta_2) \\ \vdots & \vdots \\ g_1^{l'}(r_k, \theta_k) & \dots & g_N^{l'}(r_k, \theta_k) & g_1^{ll'}(r_k, \theta_k) & g_3^{ll'}(r_k, \theta_k) & g_4^{ll'}(r_k, \theta_k) & \dots & g_M^{ll'}(r_k, \theta_k) & 0 & g_0 & g_2^{ll'}(r_k, \theta_k) \end{bmatrix} \begin{bmatrix} A_0 \\ \vdots \\ A_N \\ B_0 \\ \vdots \\ B_M \end{bmatrix} \quad (4)$$

The terms containing  $A_0$  to  $A_N$  represent the mode I part of stresses and similarly  $B_0$  to  $B_N$ , correspond to the mode II part of stresses in the William's series expansion.

### 3. Description of the biomaterial model and numerical analysis

Fig. 2 shows the geometry and loading condition of the bi-material plate with dimensions of  $20 \times 20 \times 1$  in<sup>3</sup> containing a center crack of length  $2a = 2$ in at the interface. The plate is loaded biaxialy by far field stress ( $\sigma_0$ ,  $\sigma_1$ ,  $\sigma_2$ ). Different material properties ( $E_1$ ,  $E_2$  and  $\nu_1$ ,  $\nu_2$ ) were also considered for materials 1 and 2 to investigate the effects of material types on the interface fracture parameters. Table 1 summarize different loading and material cases considered for analyzing the bi-material center crack of this research.

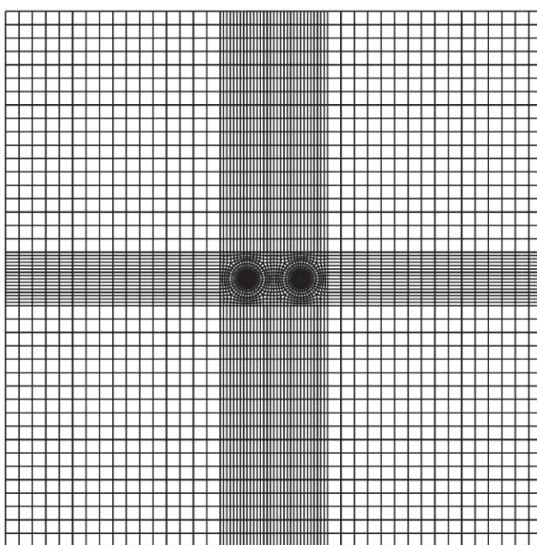


**Fig. 2.** Geometry and loading condition of a bi-material plate containing a center crack and subjected to general biaxial loading

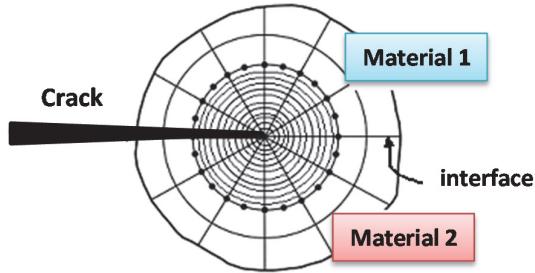
**Table 1.** Material properties and loading conditions of the investigated bi-material center cracked plate

Case. No	$E_1$ (psi)	$E_2$ (psi)	$v_1$	$v_2$	$\sigma_0$ (psi)	$\sigma_1$ (psi)	$\sigma_2$ (psi)
1	1.0	1.0	0.3	0.3	1.0	0.0	0.0
2	1.0	0.3333	0.3	0.3	1.0	1.0	0.53
3	1.0	0.1	0.3	0.3	1.0	1.0	0.37
4	1.0	0.045	0.3	0.35	1.0	1.0	0.38
5	1.0	0.01	0.3	0.3	1.0	1.0	0.31
6	1.0	0.0072	0.3	0.35	1.0	1.0	0.36
7	1.0	0.001	0.3	0.3	1.0	1.0	0.3

In order to compute three fracture parameters for the investigated interface fracture problem, it is necessary to determine the elastic stress field in the vicinity of crack tip. Based on the previous section, the nodal stress field obtained from the finite element analysis of biaxial center crack can then be inserted into the FEOD method (i.e. Eq. 4) to determine the stress intensity factors ( $K_I$  and  $K_{II}$ ) as well as the  $T$ -stress. Hence first the finite model of the center cracked plate was created using eight node plane strain elements (as shown in Fig. 3) and then a simple static FE analysis were performed for any of the cases given in Table 1.



**Fig. 3.** Finite element model of center cracked bi-material plate



**Fig. 4.** Nodal stresses considered along a ring in both materials 1 and 2 for using in FEOD method

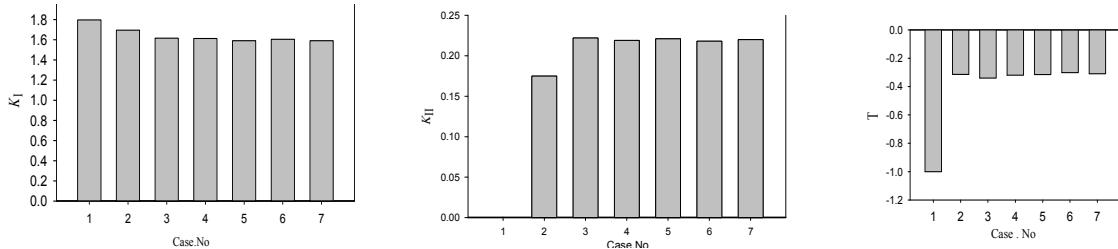
Next, as shown schematically in Fig. 4 the stress components (i.e.  $\sigma_{rr}$ ,  $\sigma_{r\theta}$ ,  $\sigma_{\theta\theta}$ ) were obtained for the entire nodes of ring with radius of  $r$  (surrounding the crack tip) as proposed in Ayatollahi and Nejati (2011).

For proper convergence of results  $r$  should be taken in the range of  $\frac{a}{4} < r < \frac{a}{2}$ , hence we considered typical value of  $r = 0.3$ in for extracting the nodal stress values. The nodal stresses were then replaced into Eq. 4, for FEOD calculation and the corresponding values of  $K_I$ ,  $K_{II}$  and  $T$  (i.e. components of matrix [X]) were determined for each case of plate model described in Table 1. The nodal stresses of upper and lower rings were also used for materials 1 and 2, respectively in Eq. 4. In the next section the obtained fracture parameters are presented and discussed.

#### 4. Results & discussion

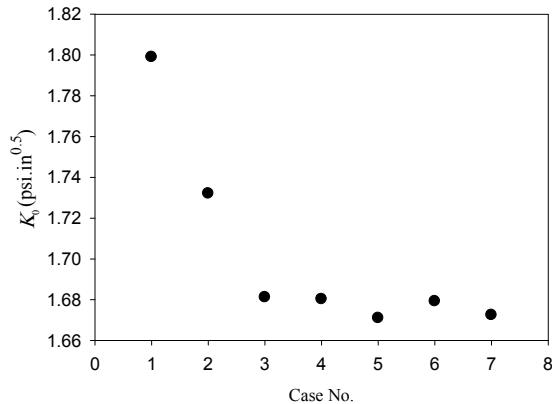
Fig. 5 shows the  $K_I$ ,  $K_{II}$  and  $T$  values for the analyzed bi-material interface center cracked plates subjected to different biaxial loads. Since materials 1 and 2 are identical in case 1 (see Table 1), this loading case represents the conventional homogenous center cracked plate under far field tension, in

which a closed form solution is available for determining its fracture parameter. Based on the pioneer work of Williams and Ewing (1972), fracture parameters of the center cracked plate under pure mode I is determined from  $K_I = \sigma_0 \sqrt{\pi a}$ ,  $K_{II} = 0$  and  $T = -\sigma_0$ . The numerical results of  $K_I$ ,  $K_{II}$  and  $T$ , computed from the FEO method is exactly identical with the analytical solution which can be considered as the validity of the numerical stress based FEO calculations. The highest value of  $K_I$  and  $T$  is obtained when the plate is homogenous. But by increasing the bi-material constant ( $\varepsilon$ ),  $K_I$  and  $T$  decrease while  $K_{II}$  becomes more.



**Fig. 5.** Corresponding values of  $K_I$ ,  $K_{II}$  (in: psi.in<sup>0.5</sup>) and  $T$  (in: psi) for different loading cases of investigated bi-material center cracked plate

The stress intensity amplitude  $K_0$ , defined by  $K_0 = \sqrt{K_I^2 + K_{II}^2}$  can be considered as a meaningful parameter in the analyzed plate, since it can be related directly to the energy release rate. Fig. 6 presents variations of  $K_0$  for different center cracked plates investigated in this research.

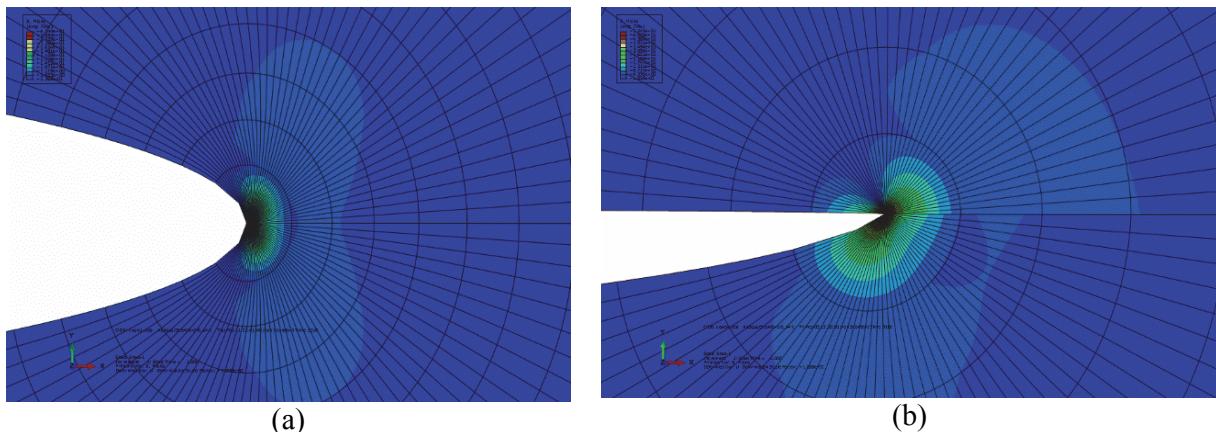


**Fig. 6.** Variations of stress intensity amplitude ( $K_0$ ) for different center cracked plates

Using the displacement field method, Chen (1985) determined the  $K_I$  and  $K_{II}$  values for the same bi-material center cracked plate. In order to compare the stress intensity factor results obtained from the stress and displacement fields, the  $K_0$  values of these two methods are presented in Table 2. It is seen that a good consistency exists between the two sets of result such that the maximum discrepancy of two methods is less than 7 %. By increasing the bi-material constant, the magnitude of  $T$ -stress, decreases noticeably implying that unlike the homogenous center crack plate, the influence of non-singular stress term are not significant for the case of bi-material problem. Furthermore, as stated earlier the case-1 in Table 1 corresponds to pure mode I loading condition because of symmetry in geometry, material and loading relative to the crack plane. However, the interface crack in other cases in Table 1 would experience mixed mode I/II loading condition due to asymmetry of material or loading relative to the interface line. Indeed, as seen from Fig. 7, while the crack tip stress contour is symmetric with respect to the interface line, the stress contour of case 4 (for instance) is not symmetric and crack experiences combined opening and sliding deformations.

**Table 2.** Comparison of  $K_0$  values determined from the stress and displacement field methods

Case. NO	Values of stress intensity amplitude ( $K_0$ )		Error %
	Present study (stress field) (psi.in <sup>0.5</sup> )	Chen(displacement field) (psi.in <sup>0.5</sup> )	
1	1.7990	1.8090	0.5559
2	1.7321	1.7980	3.8071
3	1.6812	1.7830	6.0548
4	1.6803	1.7820	6.0499
5	1.6710	1.7710	5.9871
6	1.6792	1.7790	5.9414
7	1.6725	1.7690	5.7728

**Fig. 7.** Crack tip stress contours for (a) case “1” and (b) case “4” loading conditions

## 5. Conclusions

1. Three fracture parameters of biomaterial plate containing a center crack were computed numerically under different biaxial loading cases.
2. Using the crack tip stress field and by employing the finite element over deterministic (FEOD) method,  $K_I$  and  $K_{II}$  and  $T$  stress values were computed.
3. The investigated bi-material cracked plate experiences a mixed mode opening-sliding fracture because of asymmetry in both material and loading relative to the interface line.
4. It was demonstrated that the fracture parameters of the bi-material center crack plate computed from the stress field method are accurate and very good agreement exists between the stress field and displacement field methods.
5. The amplitude of stress intensity factor ( $K_0$ ) which is related to the energy release rate becomes smaller by increasing the bi-material constant value  $\varepsilon$ .

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